

## Sensitivity analysis for the block replacement policy

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AMMSI, 20 January 2015

## Maintenance and sensitivity analysis

- Given a parametric distribution of time-to-failure (or lifetime), maintenance cost and parameters can be optimized
- When the parameters of lifetime distribution are unknown, estimation is required
- Optimal maintenance cost and parameters depend on the parameters estimation
- Estimation based on a set of time-to-failure observations
- Optimality sensitive to the estimation results
- Sensitivity analysis: necessary for an efficient maintenance planning

## Block replacement policy

- First step to propose analytical expressions for the sensitivity analysis
- Focus on the sensitivity analysis of block replacement policy
- The optimisation of this policy requires the optimization of only one parameter.

## Block replacement policy context

- Let  $T$  be the time-to-failure (or lifetime) of the device.
- The distribution of  $T$  depends on some parameter  $\theta \in \Theta \subset \mathbb{R}^p$
- Usual notations:  $f_T(\cdot; \theta)$  the probability distribution function,  $F_T(\cdot; \theta)$  the cumulative distribution function, and  $S_T(\cdot; \theta)$  the survival function (or reliability).
- No continuous monitoring (monitoring through inspections)
- At inspection time, if the device is not failed, it is replaced.
- Replacement occurs only after an inspection (in particular there is no replacement at times-to-failure)
- Replacement is AGAN
- $c_r$  the replacement cost
- $c_u$  the unavailability cost

## Block replacement policy

- This policy depends on a single parameter: the delay between two consecutive inspections  $\delta$
- Aim: define the optimal inter-inspection delay  $\delta^*$
- The asymptotic cost per unit of time defined as follows:

$$C(\delta; \theta) = \lim_{t \rightarrow \infty} \frac{C_t(\delta)}{t},$$

- $C_t(\delta)$  is the cost over the time interval  $[0, t]$  when the device is inspected at  $(k\delta)_{k \in \mathbb{N}}$

## Block replacement policy

According to the renewal theory, one has:

$$C(\delta; \theta) = \frac{\text{Expected cost over a cycle}}{\text{Expected cycle length}}.$$

For the block-replacement policy, we have:

$$C(\delta; \theta) = \frac{\mathbb{E}[c_r + c_u(\delta - T)_+]}{\delta} = \frac{c_r + c_u \int_0^\delta F_T(u; \theta) du}{\delta}.$$

Therefore,

$$\lim_{\delta \rightarrow 0} C(\delta; \theta) = +\infty \quad \text{and} \quad \lim_{\delta \rightarrow +\infty} C(\delta; \theta) = c_u.$$

Let us denote  $\delta^* := \operatorname{argmin}_{\delta > 0} C(\delta; \theta)$ . Differentiating the above expression of the cost function,  $\delta^*$  is the root of the following function (with respect to  $\delta$ ):

$$\phi(\delta; \theta) = \mathbb{E}[T \mathbf{1}_{T \leq \delta}] - \frac{c_r}{c_u}$$

where

$$\mathbb{E}[T \mathbf{1}_{T \leq \delta}] = \int_0^\delta u f_T(u; \theta) du = -\delta S_T(\delta; \theta) + \int_0^\delta S_T(u; \theta) du$$

## Block replacement policy

Under this condition of existence for  $\delta^*$ , it is well-known that the optimal cost is equal to:

$$C^* = C(\delta^*; \theta) = c_u F_T(\delta^*; \theta).$$

It follows that the optimal delay is given by:

$$\delta^* = F_T^{-1}(C^*/c_u; \theta),$$

where  $F_T^{-1}(\cdot; \theta)$  is the quantile function of the random variable  $T$ . Replacing this expression of the optimal delay in the function  $\phi$  and after some simple algebra, one can obtain an implicit function  $\psi$  satisfied by  $C^*$ :

$$\psi(C^*; \theta) = \int_0^{C^*/c_u} F_T^{-1}(u; \theta) du - \frac{c_r}{c_u} = 0.$$

## Tools for the sensitivity analysis

- Let be  $\theta_0 \in \Theta$  the true parameter of the time-to-failure distribution
- $\delta_0^*$  can be computed by determining the root of  $\phi(\cdot; \theta_0)$
- Let be  $\hat{\theta}_n$  an estimator of  $\theta$ , for instance the maximum likelihood estimator
- consistency  $\hat{\theta}_n \xrightarrow[n \rightarrow \infty]{Pr} \theta_0$ ,
- asymptotic normality:  $\sqrt{n} \left( \hat{\theta}_n - \theta_0 \right) \xrightarrow[n \rightarrow \infty]{d} \mathcal{N}(0, \Sigma_0)$ ,
- the asymptotic variance-covariance matrix  $\Sigma_0$  depends on  $\theta_0$

Key:  $\delta$ -method

when we want to replace  $\theta_0$  by  $\hat{\theta}_n$  in order to estimate  $\delta_0^*$



$\delta$ -methodTheorem ( $\delta$ -method)

Let  $(X_n)_{n \in \mathbb{N}^*}$  be a sequence of  $\mathbb{R}^p$ -valued random vectors. Assume there exists  $\mu_X \in \mathbb{R}^p$  and  $\Sigma$  a definite positive matrix such that

$$\sqrt{n}(X_n - \mu_X) \xrightarrow[n \rightarrow \infty]{d} N(0, \Sigma).$$

Let  $q$  real functions  $f_1, \dots, f_q$  with continuous first partial derivatives at  $\mu_X$ , where at least one of these derivatives is non-zero. For  $i \in \{1, \dots, q\}$  and for any  $n \in \mathbb{N}^*$ , set  $Y_{i,n} = f_i(X_n)$ ,  $Y_n = (Y_{1,n}, \dots, Y_{q,n})^T$  and  $\mu_Y = (f_1(\mu_X), \dots, f_q(\mu_X))^T$ . Then, the sequence  $(Y_n)_{n \in \mathbb{N}^*}$  is also asymptotically normal:

$$\sqrt{n}(Y_n - \mu_Y) \xrightarrow[n \rightarrow \infty]{d} N(0, K\Sigma K^T),$$

where  $K$  is the  $q \times p$  matrix with elements  $k_{i,j} = \partial f_i / \partial x_j$  for  $i \in \{1, \dots, q\}$  and  $j \in \{1, \dots, p\}$ .

## Extension of the $\delta$ -method

$\delta_0^*$  and  $C_0^*$  are the solutions of implicit equations and  $\delta$ -method not valid.  
Analogous tool for this situation proposed by Benichou and Gail:

### Theorem (Benichou and Gail 1989)

Let  $(X_n)_{n \in \mathbb{N}^*}$  be as in the previous theorem. Let  $\mu_X \in \mathbb{R}^p$  and  $\mu_Y \in \mathbb{R}^q$ . Let  $g_1, \dots, g_q$  a set of  $q$  continuous functions from  $\mathbb{R}^p \times \mathbb{R}^q$  into  $\mathbb{R}$  with continuous first partial derivatives in an open set containing  $(\mu_X, \mu_Y)$ . Let  $Y_n$  be the  $\mathbb{R}^q$ -valued random vectors satisfying  $g_r(X_n, Y_n) = 0$  for all  $r \in \{1, \dots, q\}$ . Let  $J_{X,Y}$  be the  $q \times q$  matrix with elements  $\frac{\partial g_i}{\partial y_j}(x, y)$  and let  $H_{X,Y}$  be the  $q \times p$  matrix with elements  $\frac{\partial g_i}{\partial x_j}(x, y)$ . If  $|J_{\mu_X, \mu_Y}| \neq 0$  and if each rows of  $J_{\mu_X, \mu_Y}^{-1} H_{\mu_X, \mu_Y}$  contain at least one nonzero element, then

$$\sqrt{n}(Y_n - \mu_Y) \xrightarrow[n \rightarrow \infty]{d} N(0, J_{\mu_X, \mu_Y}^{-1} H_{\mu_X, \mu_Y} \Sigma H_{\mu_X, \mu_Y}^T (J_{\mu_X, \mu_Y}^{-1})^T).$$

## Asymptotic behavior of the cost

Plug-in method:  $\forall \delta > 0, \quad C(\delta; \hat{\theta}_n) = \frac{c_r + c_u \int_0^\delta F_T(u; \hat{\theta}_n) du}{\delta}.$

### Theorem (simple application to the cost function)

Assume the hypotheses on  $\hat{\theta}_n$  are satisfied and that  $\theta \mapsto C(\delta; \theta)$  is differentiable for any  $\delta > 0$ . Let  $\nabla_\theta C(\delta; \theta)$  be the gradient vector of the cost function (with respect to  $\theta$ ). If  $\nabla_\theta C(\delta; \theta)$  is continuous and if  $\nabla_\theta C(\delta; \theta_0) \neq 0_{\mathbb{R}^p}$ , then  $C(\delta; \hat{\theta}_n)$  is an asymptotic normal (point-wise) estimator of  $C(\delta; \theta_0)$ :

$$\forall \delta > 0, \quad \sqrt{n} \left( C(\delta; \hat{\theta}_n) - C(\delta; \theta_0) \right) \xrightarrow[n \rightarrow \infty]{d} \mathcal{N}(0, \sigma_{cost}^2),$$

with  $\sigma_{cost}^2 = \nabla_\theta C(\delta; \theta_0) \Sigma_0 \nabla_\theta C(\delta; \theta_0)^T$ .

## Asymptotic behavior of the optimal inspection delay

Recall that  $\delta^*$  is the root of  $\phi(\delta; \theta)$

As an application of the previous theorems, we can also prove that  $\widehat{\delta}_n^*$  is also an asymptotically estimator of  $\delta_0^*$  under some regularity assumptions of the function  $\phi$ .

### Theorem (simple application to the optimal delay)

Assume that the hypotheses on  $\widehat{\theta}_n$  are satisfied and that  $\theta \mapsto \phi(\delta; \theta)$  is differentiable for any  $\delta > 0$ . Let  $\nabla_{\theta}\phi(\delta; \theta)$  be the gradient vector of  $\phi$  (with respect to  $\theta$ ). If  $\nabla_{\theta}\phi(\delta; \theta)$  is continuous with  $\nabla_{\theta}\phi(\delta; \theta_0) \neq \mathbf{0}_{\mathbb{R}^p}$  and if  $f_T(\delta_0^*; \theta_0) \neq 0$ , then  $\widehat{\delta}_n^*$  is an asymptotic normal estimator of  $\delta_0^*$ :

$$\sqrt{n} \left( \widehat{\delta}_n^* - \delta_0^* \right) \xrightarrow[n \rightarrow \infty]{d} \mathcal{N}(0, \sigma_{opt.delay}^2),$$

where  $\sigma_{opt.delay}^2$  is given by:

$$\sigma_{opt.delay}^2 = \frac{\nabla_{\theta}\phi(\delta_0^*; \theta_0) \Sigma_0 \nabla_{\theta}\phi(\delta_0^*; \theta_0)^T}{[\delta_0^* f_T(\delta_0^*; \theta_0)]^2}.$$

## Asymptotic behavior of the optimal inspection cost

### Theorem (simple application to the optimal cost)

Assume that the hypotheses on  $\hat{\theta}_n$  are satisfied and that  $\theta \mapsto \psi(C^*; \theta)$  is differentiable for any  $C^* > 0$ . Let  $\nabla_{\theta}\psi(C^*; \theta)$  be the gradient vector of  $\psi$  (with respect to  $\theta$ ). If  $\nabla_{\theta}\psi(C^*; \theta)$  is continuous with  $\nabla_{\theta}\psi(C_0^*; \theta_0) \neq 0_{\mathbb{R}^p}$ , then  $\hat{C}_n^*$  is an asymptotic normal estimator of  $C_0^*$ :

$$\sqrt{n} \left( \hat{C}_n^* - C_0^* \right) \xrightarrow[n \rightarrow \infty]{d} \mathcal{N}(0, \sigma_{opt.cost}^2),$$

where  $\sigma_{opt.cost}^2$  is given by:

$$\sigma_{opt.cost}^2 = \frac{c_u^2 \nabla_{\theta}\psi(C_0^*; \theta_0) \Sigma_0 \nabla_{\theta}\psi(C_0^*; \theta_0)^T}{[F_T^{-1}(C_0^*/c_u; \theta_0)]^2}.$$

The gradient function (with respect to  $\theta$ ) can also be expressed as follows:

$$\nabla_{\theta}\psi(C_0^*; \theta_0) = \int_0^{C_0^*/c_u} \nabla_{\theta} F_T^{-1}(u; \theta_0) du.$$

## Exponential time to failure

- Assume that the time-to-failure  $T$  is exponentially distributed with unknown parameter  $\lambda_0 \in \mathbb{R}_+ = \Theta$ :
- $\hat{\lambda}_n = \frac{n}{\sum_{i=1}^n T_i}$ .
- $\sqrt{n} (\hat{\lambda}_n - \lambda_0) \xrightarrow[n \rightarrow \infty]{d} \mathcal{N}(0, \lambda_0^2)$ .
- The cost function:

$$\begin{aligned} C(\delta; \lambda_0) &= \frac{1}{\delta} \left\{ c_r + c_u \int_0^\delta (1 - \exp(-\lambda_0 u)) du \right\} \\ &= \frac{1}{\delta} \left\{ c_r + c_u \delta - \frac{c_u}{\lambda_0} (1 - e^{-\lambda_0 \delta}) \right\}. \end{aligned}$$

- Optimal delay obtained by setting to zero

$$\partial_\lambda C(\delta; \lambda_0) = \frac{c_u}{\delta} \left( \frac{1}{\lambda_0^2} - \left( \frac{\delta}{\lambda_0} + \frac{1}{\lambda_0^2} \right) e^{-\lambda_0 \delta} \right).$$

$$\sigma_{cost}^2 = c_u^2 \left[ \frac{1}{\lambda_0 \delta} - \left( 1 + \frac{1}{\lambda_0 \delta} \right) e^{-\lambda_0 \delta} \right]^2.$$

## Exponential time to failure

For such distribution, it turns to be:

$$\phi(\delta; \lambda_0) = \frac{1}{\lambda_0} - \left( \delta + \frac{1}{\lambda_0} \right) e^{-\lambda_0 \delta} - \frac{c_r}{c_u}.$$

The first order partial derivatives of  $\phi$  are given by:

$$\partial_\delta \phi(\delta; \lambda_0) = \lambda_0 \delta e^{-\lambda_0 \delta}$$

$$\partial_\lambda \phi(\delta; \lambda_0) = -\frac{1}{\lambda_0^2} + \left( 1 + \frac{1}{\lambda_0 \delta} + \frac{1}{\delta^2 \lambda_0^2} \right) \delta^2 e^{-\lambda_0 \delta}.$$

It follows that the asymptotic variance is equal to:

$$\sigma_{opt.delay}^2 = \left( -\frac{e^{\lambda_0 \delta_0^*}}{\delta_0^{*2} \lambda_0^2} + \left( 1 + \frac{1}{\lambda_0 \delta_0^*} + \frac{1}{\delta_0^{*2} \lambda_0^2} \right) \delta_0^* \right)^2$$

## Exponential time to failure

At least, using the expression of the quantile function for the exponential distribution, we obtain that the optimal cost  $C_0^*$  satisfies the following equation:

$$\psi(C_0^*; \lambda_0) = \left(1 - \frac{C_0^*}{c_u}\right) \log \left(1 - \frac{C_0^*}{c_u}\right) + \frac{C_0^*}{c_u} - \lambda_0 \frac{c_r}{c_u} = 0.$$

Then, the first order partial derivatives of  $\psi$  are given by:

$$\partial_\delta \psi(C^*; \lambda_0) = -\frac{1}{c_u} \log \left(1 - \frac{C_0^*}{c_u}\right)$$

and

$$\partial_\lambda \psi(C^*; \lambda_0) = -\frac{c_r}{c_u}.$$

It follows that the asymptotic variance is equal to:

$$\sigma_{opt.cost}^2 = \left[ \frac{c_r \lambda_0^2}{\log \left(1 - \frac{C_0^*}{c_u}\right)} \right]^2.$$



## Weibull time to failure

- We consider a more general case by assuming that the time-to-failure  $T$  is Weibull distributed with parameter  $\theta_0 = (\alpha_0, \beta_0) \in \Theta = \mathbb{R}_+^2$ : The MLE are as follows:

$$\hat{\alpha}_n = \left( \frac{1}{n} \sum_{i=1}^n T_i^{\hat{\beta}_n} \right)^{\frac{1}{\hat{\beta}_n}},$$

$$\hat{\beta}_n = \left[ \left( \sum_{i=1}^n T_i^{\hat{\beta}_n} \log T_i \right) \left( \sum_{i=1}^n T_i^{\hat{\beta}_n} \right)^{-1} - \frac{1}{n} \sum_{i=1}^n \log T_i \right]^{-1}$$

- Moreover

$$(\hat{\alpha}_n, \hat{\beta}_n) \xrightarrow[n \rightarrow \infty]{d} \mathcal{N}(0, \Sigma_0)$$

where

$$\Sigma_0 = \frac{1}{\alpha_0^2(\Psi_1(1) + \Psi(2)^2 - (1 + \Psi(1))^2)} \begin{pmatrix} (\alpha_0 \beta_0)^2 & -\alpha_0(1 + \Psi(1)) \\ -\alpha_0(1 + \Psi(1)) & \frac{\Psi_1(1) + \Psi(2)^2}{\beta_0^2} \end{pmatrix}$$

## Weibull time to failure

$$\begin{aligned}
 C(\delta; \alpha_0, \beta_0) &= \frac{1}{\delta} \left\{ c_r + c_u \int_0^\delta 1 - e^{-\left(\frac{u}{\alpha_0}\right)^{\beta_0}} du \right\} \\
 &= \frac{1}{\delta} \left\{ c_r + c_u \delta - c_u \frac{\alpha_0}{\beta_0} \gamma \left( \frac{1}{\beta_0}, \left( \frac{\delta}{\alpha_0} \right)^{\beta_0} \right) \right\}.
 \end{aligned}$$

$$\partial_\alpha C(\delta; \alpha_0, \beta_0) = \frac{1}{\delta} \left\{ -\frac{c_u}{\beta_0} \gamma \left( \beta_0^{-1}, \left( \frac{\delta}{\alpha_0} \right)^{\beta_0} \right) - c_u \left( \frac{\delta}{\alpha_0} \right)^{\beta_0} \left( \left( \frac{\delta}{\alpha_0} \right)^{\beta_0} \right)^{\beta_0^{-1}-1} e^{-\left(\frac{\delta}{\alpha_0}\right)^{\beta_0}} \right\}$$

$$\partial_\beta C(\delta; \alpha_0, \beta_0) = \frac{c_u \alpha}{\delta \beta^2} \gamma \left( \beta^{-1}, \left( \frac{\delta}{\alpha} \right)^\beta \right) - \frac{c_u \alpha}{\delta \beta^3} \gamma \left( \beta^{-1}, \left( \frac{\delta}{\alpha} \right)^\beta \right) \ln \left( \left( \frac{\delta}{\alpha} \right)^\beta \right) \quad (1)$$

$$\frac{c_u \alpha}{\delta \beta^3} G_{2,3}^{3,0} \left( \left( \frac{\delta}{\alpha} \right)^\beta \mid \begin{matrix} 1,1 \\ 0,0, \beta-1 \end{matrix} \right) - \frac{c_u \alpha}{\delta \beta} \left( \frac{\delta}{\alpha} \right)^\beta \ln \left( \frac{\delta}{\alpha} \right) \left( \left( \frac{\delta}{\alpha} \right)^\beta \right)^{\beta^{-1}-1} e^{-\left(\frac{\delta}{\alpha}\right)^\beta}. \quad (2)$$

Therefore  $\sigma_{opt.cost}^2 = \nabla_\theta C(\delta; \theta_0) \Sigma_0 \nabla_\theta C(\delta; \theta_0)^T$  can be easily calculated by replacing the partial derivatives and the variance matrix.

## Weibull time to failure

Using the above identity for the finite integral of the survival function, we have:

$$\phi(\delta; \alpha_0, \beta_0) = -\delta \exp\left(-\left(\frac{\delta}{\alpha_0}\right)^{\beta_0}\right) + \frac{\alpha_0}{\beta_0} \gamma\left(\frac{1}{\beta_0}, \left(\frac{\delta}{\alpha_0}\right)^{\beta_0}\right) - \frac{C_r}{C_u}.$$

Therefore, the first order partial derivatives of  $\phi$  are as follows:

$$\partial_\delta \phi(\delta; \alpha, \beta) = -e^{-(\delta/\alpha)^\beta} + (\delta/\alpha)^\beta \beta e^{-(\delta/\alpha)^\beta} - e^{-(t/\alpha)^\beta} + \left(\frac{t}{\alpha}\right)^\beta \beta e^{-(t/\alpha)^\beta}$$

$$\partial_\alpha \phi(\delta; \alpha, \beta) = -\frac{\delta\beta}{\alpha} \left(\frac{\delta}{\alpha}\right)^\beta e^{-(\frac{\delta}{\alpha})^\beta} + \frac{1}{\beta} \gamma\left(\frac{1}{\beta}, \left(\frac{\delta}{\alpha}\right)^\beta\right)$$

$$\partial_\beta \phi(\delta; \alpha, \beta) = \delta \left(\frac{\delta}{\alpha}\right)^\beta \ln\left(\frac{\delta}{\alpha}\right) e^{-(\frac{\delta}{\alpha})^\beta} - \frac{\alpha}{\beta^2} \gamma\left(\frac{1}{\beta}, \left(\frac{\delta}{\alpha}\right)^\beta\right)$$

$$\sigma_{opt.delay}^2 = \frac{\nabla_\theta \phi(\delta_0^*; \theta_0) \Sigma_0 \nabla_\theta \phi(\delta_0^*; \theta_0)^T}{[\delta_0^* f_T(\delta_0^*; \theta_0)]^2}.$$

where  $f(x; \alpha, \beta) = \frac{\beta}{\alpha} \left(\frac{x}{\alpha}\right)^{\beta-1} e^{-(x/\alpha)^\beta}$  is known

## Weibull time to failure

For the Weibull distribution,

$$\forall t \geq 0, \quad F_T(t, \theta) = 1 - \exp\left(-\left(\frac{t}{\alpha_0}\right)^{\beta_0}\right).$$

Therefore  $\delta^* = \alpha_0(-\ln(1 - C^*/c_u))^{1/\beta_0}$ , where

$$\frac{\partial F_T^{-1}(C^*/c_u, \theta_0)}{\partial \alpha_0} = -\ln(1 - C^*/c_u)^{1/\beta_0}$$

and

$$\frac{\partial F_T^{-1}(C^*/c_u, \theta_0)}{\partial \beta_0} = \frac{\alpha_0 \ln(1 - C^*/c_u)^{1/\beta_0} \ln(\ln(1 - C^*/c_u))}{\beta_0^2}$$

Therefore we can calculate,

$$\sigma_{opt.cost}^2 = \frac{c_u^2 \int_0^{C_0^*/c_u} \nabla_{\theta} F_T^{-1}(u; \theta_0) du \Sigma_0 \int_0^{C_0^*/c_u} \nabla_{\theta} F_T^{-1}(u; \theta_0) du^T}{[F_T^{-1}(C_0^*/c_u; \theta_0)]^2}.$$

Thank you for your attention